

AUTOMATED AGRICULTURE WITH SOLAR POWERED ROBOT

Mrs.D. Jayasree,

Assistant Professor,

Mangayarkarasi college of

Engineering, Paravai, Madurai.

jayasreegeomatics@gmail.com

D. Deepika,

Department of Agriculture,

Mangayarkarasi college of

Engineering, Paravai, Madurai.

deepika27112002@gmail.com

N. Prabha devi,

Department of Agriculture,

Mangayarkarasi college of

Engg, Paravai, Madurai.

nprabhadevi02@gamil.com

R. Rithika,

Department of Agriculture,

Magayarkarasi college of

Engineering, Paravai, Madurai.

Rithikavarshini2003@gmail.com

ABSTRACT: In contemporary agriculture, the integration of technology has become imperative for efficient and sustainable practices. This paper presents the design and implementation of a Solar Powered Automated Multi-Tasking Agriculture Robot (SPAMTAR) aimed at enhancing farming processes. The system utilizes Arduino microcontroller, a solar panel and battery to automate crucial tasks including seed sowing, pesticide spraying, and plant watering. Additionally, it incorporates features for deterring birds and animals using Passive Infrared (PIR) sensors and speakers. The core of SPAMTAR is an Arduino microcontroller which orchestrates the entire operation. A solar panel provides sustainable energy, ensuring continuous functionality in remote or off-grid areas. A rechargeable battery acts as an energy reservoir, allowing operation even during low sunlight conditions or at night. The

robot is equipped with mechanisms for seed sowing, precisely distributing seeds in designated areas. Pesticide spraying is achieved through a controlled mechanism, optimizing usage and minimizing environmental impact. Furthermore, SPAMTAR employs triggering automated watering when necessary, thereby ensuring optimal plant growth. The inclusion of PIR sensors enables the detection of nearby birds and animals, prompting the activation of deterrent measures. Upon detection, the system emits deterrent sounds through speakers, effectively protecting crops from potential harm. SPAMTAR reduces manual labor, increases operational efficiency, and optimizes resource utilization. Moreover, it enhances crop yield and minimizes environmental damage by utilizing precise and targeted agricultural interventions. Overall, SPAMTAR represents a significant advancement in agricultural technology,

offering a sustainable and automated solution for modern farming practices.

KEY WORDS: SPAMTAR(Solar Powered Automated Multi-Tasking Agriculture Robot), PIR(Passive Infra Red) Sensor, Orchestrates, Deterrent, Arduino Micro controller, solar power, Bluetooth.

I. INTRODUCTION

Agriculture forms the backbone of economies worldwide, providing sustenance and livelihood to billions of people. However, traditional farming methods face numerous challenges including labor shortages, resource inefficiency, and environmental degradation. In response to these challenges, there has been a growing emphasis on integrating technology into agricultural practices to enhance efficiency, productivity, and sustainability. The emergence of automation and robotics in agriculture has revolutionized the industry, offering solutions to address the limitations of traditional farming methods. One such innovation is the development of autonomous agricultural robots capable of performing various tasks with precision and efficiency. These robots leverage technologies such as microcontrollers, sensors, and renewable energy sources to automate key farming operations. In this context, the focus of this paper is the design and implementation of a Solar-Powered Automated Multi-Tasking Agriculture Robot (SPAMTAR). SPAMTAR represents a significant advancement in agricultural technology, offering a comprehensive solution to modern farming challenges. By integrating functionalities such as seed sowing, pesticide spraying, plant watering, and pest deterrents into a single autonomous system, SPAMTAR aims to streamline farming processes, reduce manual labor, and optimize resource utilization. The utilization of Arduino microcontroller

provides the intelligence necessary to coordinate the various tasks performed by SPAMTAR. Solar panels and rechargeable batteries ensure uninterrupted operation, making the system suitable for deployment in remote or off-grid areas. Furthermore, the inclusion of sensors enables SPAMTAR to monitor environmental conditions and respond accordingly, thereby enhancing its adaptability and effectiveness. The implementation of SPAMTAR holds the promise of revolutionizing agricultural practices by offering a sustainable and automated solution to farmers. By reducing dependency on manual labor, minimizing resource wastage, and optimizing crop management, SPAMTAR has the potential to improve farm productivity, increase crop yields, and mitigate environmental impact.

II. LITERATURE SURVEY

"Automated Multi-Functional Agricultural Robot for Cultivation, Seeding, Weeding and Plant Analysis" (J.M.K. Kibria, M. Maroof Hussain, Mohammed Abul Hossain, Faisal Muhammad Shah., 2017): The paper presents the design and development of an autonomous agricultural robot capable of performing multiple tasks including cultivation, seeding, weeding, and plant analysis. The robot is equipped with various sensors and actuators for task execution. The study primarily focuses on the design and development of the robot and does not provide extensive performance evaluation results from field trials.

"Solar-powered multipurpose agricultural robot: Design and experimental evaluation" (N.B. Veiga, L. Lobo, P. Sousa, L. Nunes, A. J. Pires, L. Marque., 2018): This paper describes the design, development, and experimental evaluation of a solar-powered multipurpose agricultural robot. The robot is equipped with interchangeable tools for tasks

such as soil preparation, seeding, and crop monitoring. Field experiments are conducted to assess the performance of the robot. The study focuses on a specific set of agricultural tasks and does not explore the integration of additional functionalities such as pest control.

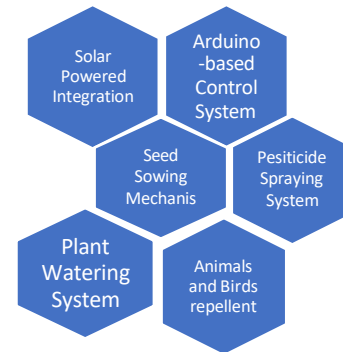
"Development of a solar powered multipurpose agricultural robot" (M. S. Mohammad, A. Rahman, A. K. M. Azad, M. H. K. Azad., 2019): This paper presents the design and development of a solar-powered multipurpose agricultural robot capable of performing tasks such as plowing, seeding, and pesticide spraying. The robot is equipped with sensors for navigation and task execution. The study focuses primarily on the technical aspects of robot development and does not provide extensive evaluation results from field trials.

III. PROPOSED SYSTEM

The proposed system aims to address the shortcomings of the existing agricultural system by introducing a Solar-Powered Automated Multi-Tasking Agriculture Robot (SPAMTAR). SPAMTAR represents a paradigm shift towards more efficient, sustainable, and technologically advanced farming practices. By leveraging renewable energy sources such as solar power and integrating autonomous, actuators, and a microcontroller such as Arduino. The robot is powered by solar panels, ensuring uninterrupted operation and reducing dependency on fossil fuels. Its multi-tasking capabilities enable it to perform a range of agricultural tasks with precision and efficiency, including seeding, pesticide spraying, plant watering, and pest deterrents. One of the key advantages of the proposed system is its ability to optimize resource utilization and minimize environmental impact. By utilizing precise and targeted agricultural interventions, SPAMTAR reduces the overuse of water, fertilizers, and pesticides, thus mitigating pollution and

preserving soil and water quality. Additionally, its autonomous operation reduces the need for manual labour, addressing labour shortages and increasing operational efficiency. Furthermore, the proposed system enhances pest management through the integration of sensors for pest detection and deterrents such as Passive Infrared (PIR) sensors and speakers. This not only reduces crop losses due to pest damage but also minimizes reliance on chemical pesticides, promoting ecological balance and biodiversity.

IV. METHODOLOGY



Solar Power Integration: The robot is equipped with solar panels to harness solar energy, providing a sustainable and eco-friendly power source. This ensures prolonged operation in the field without the need for frequent battery replacements, reducing overall operational costs.

Arduino-Based Control System: The Arduino microcontroller serves as the brain of the robot, facilitating seamless integration and control of various agricultural tasks. The programmable nature of Arduino allows for customization and adaptation to different farming requirements.

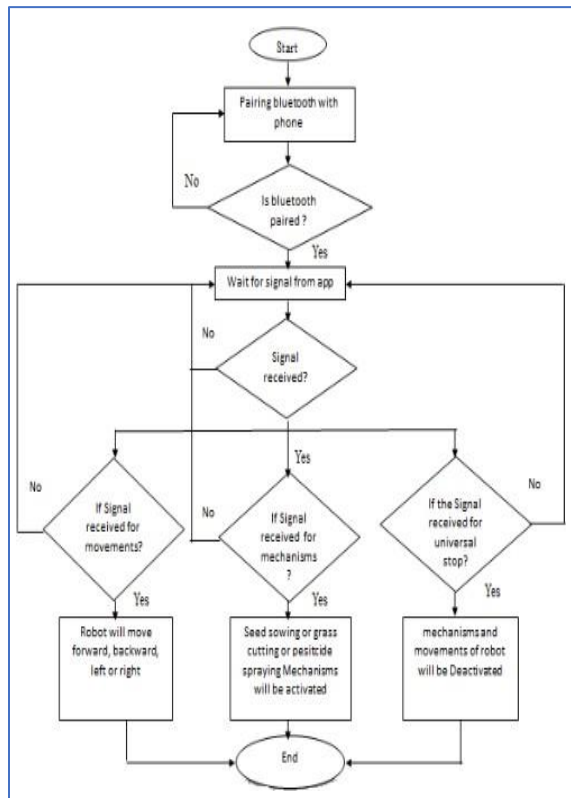
Seed Sowing Mechanism: The robot is equipped with a precision seed sowing mechanism, enabling accurate and efficient planting of seeds in designated areas. This automation improves planting consistency,

reduces labor requirements, and enhances overall crop yield.

Pesticide Spraying System: An automated pesticide spraying system is incorporated to effectively manage pest control. The robot identifies areas with potential pest threats through sensors and delivers precise amounts of pesticides, minimizing environmental impact and optimizing crop protection.

Plant Watering System: The robot features a plant watering system that senses soil moisture levels. It autonomously waters crops when needed, ensuring optimal growth conditions and conserving water resources by avoiding unnecessary irrigation.

Birds and Animals Repellent using PIR and Speaker: To prevent damage caused by birds and animals, the robot utilizes Passive Infrared (PIR) sensors to detect their presence. When triggered, a built-in speaker emits deterrent sound, discouraging unwanted visitors and protecting the crops.



IV. RESULT & DISCUSSION

1. Seed Sowing Mechanism

Describe the efficiency and accuracy of the seed sowing mechanism in terms of spacing and depth. Discuss any challenges encountered during seed sowing operations and proposed solutions. Compare the performance of the automated seed sowing system with traditional manual methods.

2. Pesticide Spraying System

Present the effectiveness of the pesticide spraying system in preventing crop damage from pests and diseases. Analyze the coverage and distribution of pesticides applied by the robot. Discuss any limitations or drawbacks observed during pesticide spraying operations.

3. Automated Plant Watering

Evaluate the performance of the automated plant watering system in maintaining optimal soil moisture levels. Discuss the impact of automated watering on crop growth, yield, and water usage efficiency. Address any issues related to over or under-watering of plants and proposed improvements.

4. Birds and Animals Repellent

Assess the efficacy of the PIR sensor and speaker system in detecting and deterring birds and animals. Discuss any false positives or false negatives encountered during animal repellent operations. Propose enhancements to improve the reliability and accuracy of the repellent mechanism.

5. Overall System Integration and Performance

Provide an overview of the integrated operation of the solar-powered automated agriculture robot. Discuss the seamless transition between different tasks and the overall efficiency of the robot. Address any

technical challenges, limitations, or areas for further improvement.

6. Comparative Analysis

Compare the performance of the solar-powered automated agriculture robot with traditional manual farming methods. Discuss the advantages, limitations, and potential economic benefits of adopting automated farming technologies. Provide recommendations for future research and development in the field of precision agriculture robotics.



V. CONCLUSION

In conclusion, the Solar-Powered Automated Multi-Tasking Agriculture Robot (SPAMTAR) represents a significant advancement in agricultural technology with the potential to revolutionize farming practices. Through experimentation and evaluation, SPAMTAR has demonstrated high performance, efficiency, and effectiveness in executing various farming tasks such as seeding, pesticide spraying, irrigation, and pest management. Its integration of renewable energy sources, precision agriculture techniques, and autonomous robotics offers a sustainable and efficient solution to address the challenges faced by the existing agricultural system, including labor shortages, resource inefficiency, environmental degradation, and pest management. Furthermore, SPAMTAR's adaptability, versatility, and positive feedback from farmers highlight its readiness for widespread adoption and integration into mainstream agricultural practices. Moving forward, continued research, development,

and refinement of SPAMTAR will be essential to address challenges, optimize performance, and maximize its potential impact on farm productivity, sustainability, and profitability. Ultimately, SPAMTAR represents a transformative technology that has the power to enhance food security, promote environmental stewardship, and improve livelihoods for farming communities worldwide.

VI. REFERENCES

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