

Original Article

Back Stepping Algorithm Used By Electrical Vehicle Photovoltaic Charge Controller

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Abstract: The electric vehicles are widely used in transport system in present day. It is pollution less and cost effective transport method. The ultimate aim of the project is to design and development of solar charge controller for electric vehicle. The battery is the primary source of electric vehicle since the proposed method is to charge the battery properly by using back stepping algorithm. The pic16f877a microcontroller used to measure photo voltaic (PV) panel output and boost converter output and generate pulse width modulation (PWM) signal to control boost converter for proper charging of battery.

Keywords: Solar, Boost Converter, Pic16f877a and PWM.

INTRODUCTION

The performance of smart charge controller system is used to extend the life time of battery for electric vehicle. When the battery energy is deficient then the energy is importing from solar PV panel. When the battery energy is excess then energy is exporting to the electric vehicle.

PROPOSED METHOD

The proposed system is uses pic16f877a microcontroller because it has built in analog to digital converter (ADC) and pulse width modulator (PWM). Generally the boost converter placed at the load side but in our proposed system uses boos converter in between solar PV array and battery. Because of the battery should charge properly for increases battery life.

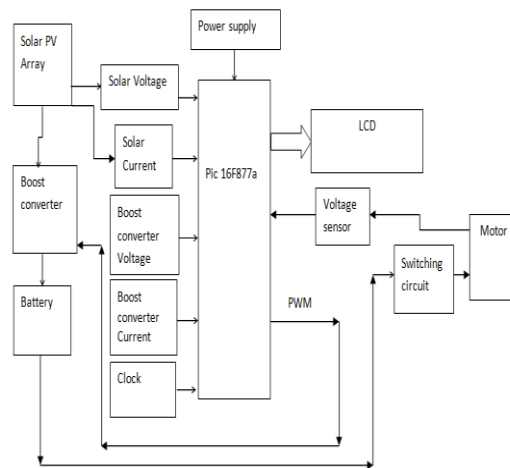


Fig.1. Block diagram of charge controller

The voltage and current sensor connected with ADC channel of Pic16f877a micro controller. The 16 character and 2 line alphanumeric display is used for monitoring the solar voltage, solar current, boost converter output voltage , boost converter output current. The Fig.1 shows the block diagram of proposed charge controller system. The Fig. 2 shows the circuit diagram of project. It has reset circuit, oscillator circuit, boost converter circuit, and LCD circuit.



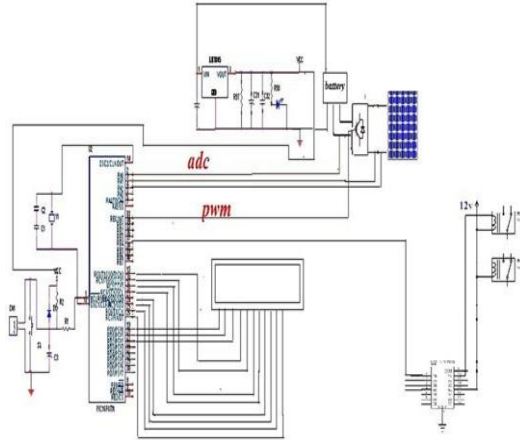


Fig.2. Circuit diagram of charge controller

The algorithm measures the error between output power and required power. The PWM adjust the boost converter output due to required power

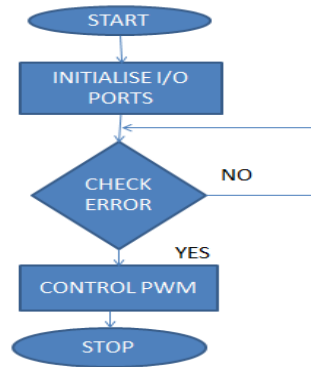


Fig.3. Flow of charge controller

$$I_{PV} = N_P I_{PV} - N_P I_{S \exp} \frac{V_{PV} + R_S I_{PV}}{-1} - N_P q \frac{V_{PV} + R_S I_{PV}}{-1}$$

Parameter	Name	Value
P_{MAX}	Maximum Power	100Wp
V_{mp}	Voltage at maximum power	18.7V
I_{mp}	Current at maximum power	5.39A
V_{OC}	Open circuit voltage	21.6V
I_{SC}	Short circuit current	5.87A
k_i	Temperature coefficient of I_{SC}	1.73mA/°C
n_s	Number of cells per module	60

ADVANTAGES

- It uses renewable energy source
- Less cost
- Emission less
- It completely reduces pollution.
- SIMULATION AND RESULT

- The simulation result of this concept is verified by proteus 8 professional software.

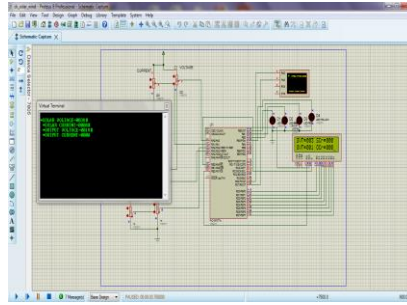


Fig.4. simulation of proteus software

The software has built in library for pic16f877a, LCD, serial terminal, analog and digital inputs/ outputs. The micro controller embedded c code is converted into .hex file format. The pot connected to the ADC channel for voltage and current analog input simulation.



Fig.5. experimental charge controller

The experimental hardware has same .hex file loaded into the pic16f877a. It has relay driver ic (ULN2003) for driving electromagnetic relay. The electromagnetic relay used for driving dc motor. The experimental hardware has 12V/2.5A battery with 6W solar panel.

CONCLUSION

The EV charging controller is proposed and its performance is analyzed by experimental output. The proposed controller examined the output power requirement of boost converter for proper charging. The back stepping algorithm is better to adjust the PWM for required output. The PWM is controls the boost converter for required output power.

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